# **Fuzing for Global Interoperability**



- Cockpit Programming to Reduce Logistics
- Distributed Arming Systems for Missiles
- Tolerant Burst Point Control

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## **Future Cockpit Programming**



#### **Present programming**

- Mission planning tools program a PCMCIA card
- PCMCIA card sent to fuze programming site or Mission data sent to fuze programming site and program a PCMCIA card
- Setter unit programs fuze on ground
- Fuze's program checksums hand written on weapon
- Weapon loaded onto specific location of aircraft
- In-flight, fuze mission data can be reprogrammed
- Pilot selects proper weapon from aircraft stores
- Launch weapon

#### **Future programming**

- Mission planning develops mission data
- Mission data sent to aircraft
- Aircraft programs fuze, including weapon type
- Launch weapon

## **Cockpit Programming Improvements**



- Reduce Tactical Response Time by eliminating Ground Programming Processes
- Increase Reliability of Launching Proper Weapon from Aircraft.
   Prevent Launching Weapon with Wrong Mission Data at a Target,
   when can't Interrogate Weapon on Aircraft
- Eliminate Hardware, I.e. Ground Setter Unit
- Eliminate Training, I.e. Ground Setter Unit Training
- Eliminate Maintenance I.e. Ground Setter Unit Maintenance
- Increase Fuze Connector Life and Reliability
  - Reduce Number of Connections to Fuze

# **Cockpit Programming Plan**



- Develop System Safety Approach to program Mission and Weapon Type Parameters
- Obtain Safety Board Approval of Approach
- Implement Approach
- Obtain Safety Board Approval of Design

## **Distributed Arming Systems**



- Reason for a Distributed Arming System
  - Fuze does not have access to Arming Environments, like when Fuze is buried in a Missile
- Core Requirements for Distributed Arming System
  - MIL-STD-1316 requires Two Independent Arming Environments that Independently Control Arming
    - Hardware only (No Software) in at Least One Arming Environment Path
  - Unique Code for Arming

# **Examples of Distributed Arming Systems**



- Free-Flight and Guided Bomb Systems
  - FMU-139 and FZU-48
  - FMU-152 and FZU-55
  - HTSF and FZU-60
- BAT: Umbilical Separation, Air Stream Sensing, and ESAD
- TTPV with a HTSF
- CALCM with a HTSF
- Others

### **FZU Distributed Arming Systems**



- FZU detects Two Independent Arming Environments
  - Lanyard Pull
    - Minimum Lanyard Pull Force
    - FZU Time Windows the Turbine Release Arming Environment
  - FZU Powers Fuze with Post Launch Air Stream
- Unique Power & Turbine Release Signals from FZU-48 & FZU-55
  - Positive for Power
  - Negative for Turbine Release
- FZU-60 Power and Turbine Release Frequencies verified with HTSF & MEHTF

## **Missile Distributed Arming Systems**



- Missile programs Fuze
- Missile detects Arming Environments
- Missile builds Unique Arm Code with Arming Environment Data
- Missile provides Arming Power to Fuze
- Missile provides Unique Arm Code to Fuze
- Fuze arms after
  - Timing out Arm Time
  - Detecting Unique Arm Code

## **Unique Arm Code**



- Probability of Occurrence << One in a Million to meet MIL-STD-1316's Less than One in a Million arm before launch for System
- Ignores Common signals
  - •Common power: DC, 110Vac. 60hz; 110Vac, 400hz
  - Low Frequency Guidance Signals
- Provides Immunity to Electromagnetic Environments (HERO, EMV, Other)
- Built using arming environments like
  - Launch
  - Deployment of Air Surfaces
  - Post Launch Air Stream or Engine Power
  - Other

### **Tolerant Burst Point Control**

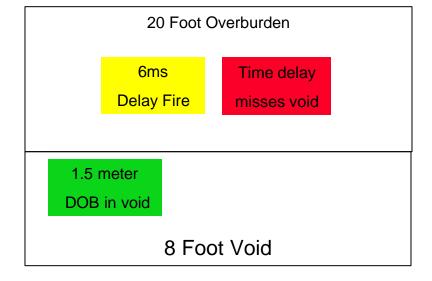


- Void Detection of HTSF and MEHTF provide Accurate Depth of Burial for
  - Varying Overburden
  - Multiple Voids
  - Unknown Void Lengths

#### **HTSF & MEHTF Void Burst Point Control**



- Void depth of burial makes target defeat economical with Tolerant burst point control
- DOB from void entry fires warhead in void without accurate target intelligence
  - Prevents fires before and after voids
  - Reduces DOB errors from variations in overburden, impact angles, angle of attack, impact velocity, and warhead turning during penetration



Some fuzes
miss void due to
g switch delay
to detect impact

26ms Delay Fire